

## On the group of extensions for the bicrossed product construction for a locally compact group

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**ABSTRACT.** For the cocycle bicrossed product construction applied to a locally compact group and its two subgroups, we give a simple description of the group of the corresponding extensions in terms of the second cohomology group of a certain complex of continuous functions on the group. Using this description, we find pairs of continuous cocycles for two subgroups of the Heisenberg group.

### Introduction

A method for constructing nontrivial examples of finite ring groups, now known as finite Kac algebras, was proposed in [1]. It consists in using two subgroups of a group satisfying certain conditions for constructing a commutative algebra of functions on one subgroup and then extending it to a nontrivial Kac algebra, via a pair of cocycles, with the group algebra of the other subgroup. This method is now called the bicrossed product construction and was generalized to bialgebras in [2] and to locally compact quantum groups in [3].

For fixed subgroups, the set of extensions forms a group whose elements are determined by equivalence classes of pairs of cocycles. This group formed by equivalence classes of pairs of measurable functions is

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described in [4] for a locally compact group in terms of the second cohomology group of a certain complex constructed from a bicomplex.

The purpose of this paper is to consider the case where the extensions are obtained using continuous cocycles and to give a simple direct construction of a complex such that its second cohomology group is isomorphic to the group of such extensions. This is done in Section 1 after first making necessary definitions. In Section 2 we use this result and the ideas from [5] to construct pairs of cocycles for two subgroups of the Heisenberg group.

### 1. Definitions and the main result

**Definition 1** ([6]). Let  $K$  be a locally compact group,  $G, H$  subgroups of  $K$  satisfying the conditions

$$G \cdot H = K \quad \text{and} \quad G \cap H = \{e\}.$$

Then  $(G, H)$  is called a matched pair of locally compact groups.

**Remark 1.** For a more general definition of a matched pair of locally compact groups, see [3].

In what follows,  $g, h, k$  with, possibly, subscripts denote elements of the groups  $G, H, K$ , respectively.

Let  $(G, H)$  be a matched pair of locally compact groups. It is known [3] that there are right and left actions,  $\triangleleft : H \times G \rightarrow H$  and  $\triangleright : H \times G \rightarrow G$ , given by

$$h \cdot g = (h \triangleright g) \cdot (h \triangleleft g)$$

and satisfying

$$\begin{aligned} (h_1 h_2) \triangleleft g &= (h_1 \triangleleft (h_2 \triangleright g))(h_2 \triangleleft g), \\ h \triangleright (g_1 g_2) &= (h \triangleright g_1)((h \triangleleft g_1) \triangleright g_2). \end{aligned} \tag{1}$$

Denote  $\mathbb{T} = \{z \in \mathbb{C} : |z| = 1\}$  and let  $\tilde{\mathbb{T}}$  be the Abelian group  $\mathbb{R}/2\pi\mathbb{Z}$ .

**Definition 2** ([3]). Let  $(G, H)$  be a matched pair of locally compact groups. A pair of continuous maps  $(u, v)$ ,  $u : H \times G \times G \rightarrow \mathbb{T}$ ,  $v : H \times H \times G \rightarrow \mathbb{T}$  is called a pair of cocycles for the pair  $(G, H)$  if the following identities hold:

$$u(h \triangleleft g_1, g_2, g_3)u(h, g_1, g_2 g_3) = u(h, g_1, g_2)u(h, g_1 g_2, g_3), \tag{2}$$

$$v(h_1, h_2, h_3 \triangleright g)v(h_1 h_2, h_3, g) = v(h_1, h_2 h_3, g)v(h_2, h_3, g), \tag{3}$$

$$\begin{aligned} v(h_1, h_2, g_1 g_2)u(h_1 h_2, g_1, g_2) &= v(h_1, h_2, g_1)u(h_2, g_1, g_2) \\ &\quad \cdot v(h_1 \triangleleft (h_2 \triangleright g_1), h_2 \triangleleft g_1, g_2) \\ &\quad \cdot u(h_1, h_2 \triangleright g_1, (h_2 \triangleleft g_1) \triangleright g_2). \end{aligned} \tag{4}$$

Two pairs of cocycles  $(u_1, v_1)$  and  $(u_2, v_2)$  for  $(G, H)$  are called equivalent if there exists a continuous function  $r : H \times G \rightarrow \mathbb{T}$  such that

$$\begin{aligned} u_1(h, g_1, g_2)u_2(h, g_1, g_2)^{-1} &= r(h, g_1)r(h \triangleleft g_1, g_2)r(h, g_1g_2)^{-1}, \\ v_1(h_1, h_2, g)v_2(h_1, h_2, g)^{-1} &= r(h_1h_2, g)r(h_1, h_2 \triangleright g)^{-1}r(h_2, g)^{-1}. \end{aligned} \quad (5)$$

We will denote the equivalence class of a pair  $(u, v)$  by  $[u, v]$ . It is known [3] that the set of equivalence classes  $[u, v]$  forms a group with respect to the operations  $[u_1, v_1] \cdot [u_2, v_2] = [u_1u_2, v_1v_2]$ ,  $[u, v]^{-1} = [u^{-1}, v^{-1}]$ , and the identity element  $[1, 1]$ . We will consider the subgroup of this group formed by the classes  $[u, v]$  such that  $u(h_1, g_2, g_3) = 1$  if at least one of the elements  $h_1, g_2, g_3$  is the identity of the corresponding group and the same holds for  $v$ . This subgroup will be denoted by  $H_0^2(\text{m.p.}, \mathbb{T})$ .

Let  $(G, H)$  be a matched pair of locally compact groups. Denote by  ${}_G C_H^n(K^{n+1}, \mathbb{T})$ , or simply by  ${}_G C_H^n(K)$ ,  $n = 0, 1, \dots$ , the set of continuous functions  $c^n : K^{n+1} \rightarrow \mathbb{T}$  such that

$$c^n(gk_1, k_2, \dots, k_n, k_{n+1}h) = c^n(k_1, k_2, \dots, k_n, k_{n+1}), \quad (6)$$

$$c^n(k_1, \dots, k_{j-1}, e_K, k_{j+1}, \dots, k_{n+1}) = 0 \quad (7)$$

for all  $g \in G$ ,  $h \in H$ ,  $k_j \in K$ ,  $j = 1, \dots, n+1$ . Here  $e_K$  denotes the identity element in  $K$ .  ${}_G C_H^n$  is an Abelian group with respect to the pointwise addition. As usual [7], define

$$\begin{aligned} (d^n c^n)(k_1, \dots, k_{n+2}) &= c^n(k_2, \dots, k_{n+2}) \\ &+ \sum_{j=1}^{n+1} (-1)^j c^n(k_1, \dots, k_j k_{j+1}, \dots, k_{n+2}) \\ &+ (-1)^{n+2} c^n(k_1, \dots, k_{n+1}) \end{aligned} \quad (8)$$

and thus obtain the following complex:

$${}_G C_H^0(K) \xrightarrow{d^0} {}_G C_H^1(K) \xrightarrow{d^1} {}_G C_H^2(K) \xrightarrow{d^2} {}_G C_H^3(K) \xrightarrow{d^3} \dots, \quad (9)$$

where, as easily seen,  ${}_G C_H^0(K)$  can be identified with the group that has the only element 0 and  ${}_G C_H^1(K)$  with the group of all continuous functions  $c^1$  on  $K$  satisfying  $c^1 \upharpoonright_G = c^1 \upharpoonright_H = 0$ .

**Theorem.** Let  ${}_G H_H^2(K) = \text{Ker } d^2 / \text{Im } d^1$  denote the second cohomology group of complex (9). Then the map  $\theta : H_0^2(\text{m.p.}, \mathbb{T}) \rightarrow {}_G H_H^2(K)$  defined by

$$\theta([u, v])(k_1, k_2, k_3) = \frac{1}{i} \ln u(h_1, g_2, h_2 \triangleright g_3) + \frac{1}{i} \ln v(h_1 \triangleleft g_2, h_2, g_3), \quad (10)$$

is a group isomorphism. Here  $\ln: \mathbb{T} \rightarrow i\tilde{\mathbb{T}}$  is the principle branch of the logarithm,  $k_j = g_j h_j$ ,  $j = 1, 2, 3$ , and  $i = \sqrt{-1}$ .

The proof of the theorem will be divided into several lemmas. But before, let us denote  $\tilde{u} = \frac{1}{i} \ln u$ ,  $\tilde{v} = \frac{1}{i} \ln v$ , and  $\tilde{r} = \frac{1}{i} \ln r$ . With these notations, the map (10) becomes

$$\theta([u, v])(k_1, k_2, k_3) = \tilde{u}(h_1, g_2, h_2 \triangleright g_3) + \tilde{v}(h_1 \triangleleft g_2, h_2, g_3), \quad (11)$$

the defining relations (2), (3), (4) will read

$$\tilde{u}(h \triangleleft g_1, g_2, g_3) - \tilde{u}(h, g_1 g_2, g_3) + \tilde{u}(h, g_1, g_2 g_3) - \tilde{u}(h, g_1, g_2) = 0, \quad (12)$$

$$\tilde{v}(h_2, h_3, g) - \tilde{v}(h_1 h_2, h_3, g) + \tilde{v}(h_1, h_2 h_3, g) - \tilde{v}(h_1, h_2, h_3 \triangleright g) = 0, \quad (13)$$

$$\begin{aligned} \tilde{v}(h_1, h_2, g_1 g_2) + \tilde{u}(h_1 h_2, g_1, g_2) &= \tilde{v}(h_1, h_2, g_1) + \tilde{v}(h_1 \triangleleft (h_2 \triangleright g_1), h_2 \triangleleft g_1, g_2) \\ &+ \tilde{u}(h_2, g_1, g_2) + \tilde{u}(h_1, h_2 \triangleright g_1, (h_2 \triangleleft g_1) \triangleright g_2), \end{aligned} \quad (14)$$

and the equivalence relations (5) are

$$\begin{aligned} \tilde{u}_1(h, g_1, g_2) - \tilde{u}_2(h, g_1, g_2) &= \tilde{r}(h, g_1) + \tilde{r}(h \triangleleft g_1, g_2) - \tilde{r}(h, g_1 g_2), \\ \tilde{v}_1(h_1, h_2, g) - \tilde{v}_2(h_1, h_2, g) &= \tilde{r}(h_1 h_2, g) - \tilde{r}(h_1, h_2 \triangleright g) - \tilde{r}(h_2, g). \end{aligned} \quad (15)$$

**Lemma 1.** *Let a pair  $(\tilde{u}, \tilde{v})$  satisfy (12), (13), (14), and*

$$f(k_1, k_2, k_3) = \tilde{u}(h_1, g_2, h_2 \triangleright g_3) + \tilde{v}(h_1 \triangleleft g_2, h_2, g_3), \quad (16)$$

$k_j = g_j h_j$ ,  $j = 1, 2, 3$ . Then  $f$  is a 2-cocycle for the complex (9).

*Proof.* Indeed, by the definition of  $f$ , for  $k_j = g_j h_j$ ,  $j = 1, \dots, 4$ , we have

$$\begin{aligned} (d^2 f)(k_1, k_2, k_3, k_4) &= f(k_2, k_3, k_4) - f(k_1 k_2, k_3, k_4) + f(k_1, k_2 k_3, k_4) \\ &\quad - f(k_1, k_2, k_3 k_4) + f(k_1, k_2, k_3) \\ &= f(g_2 h_2, g_3 h_3, g_4 h_4) - f(g_1 (h_1 \triangleright g_2) (h_1 \triangleleft g_2) h_2, g_3 h_3, g_4 h_4) \\ &\quad + f(g_1 h_1, g_2 (h_2 \triangleright g_3) (h_2 \triangleleft g_3) h_3, g_4 h_4) \\ &\quad - f(g_1 h_1, g_2 h_2, g_3 (h_3 \triangleright g_4) (h_3 \triangleleft g_4) h_4) + f(g_1 h_1, g_2 h_2, g_3 h_3) \\ &= \tilde{u}(h_2, g_3, h_3 \triangleright g_4) + \tilde{v}(h_2 \triangleleft g_3, h_3, g_4) - \tilde{u}((h_1 \triangleleft g_2) h_2, g_3, h_3 \triangleright g_4) \\ &\quad - \tilde{v}(((h_1 \triangleleft g_2) h_2) \triangleleft g_3, h_3, g_4) + \tilde{u}(h_1, g_2 (h_2 \triangleright g_3), ((h_2 \triangleleft g_3) h_3) \triangleright g_4) \\ &\quad + \tilde{v}(h_1 \triangleleft (g_2 (h_2 \triangleright g_3)), (h_2 \triangleleft g_3) h_3, g_4) - \tilde{u}(h_1, g_2, h_2 \triangleright (g_3 (h_3 \triangleright g_4))) \\ &\quad - \tilde{v}(h_1 \triangleleft g_2, h_2, g_3 (h_3 \triangleright g_4)) + \tilde{u}(h_1, g_2, h_2 \triangleright g_3) + \tilde{v}(h_1 \triangleleft g_2, h_2, g_3). \end{aligned}$$

Replacing  $h_1$ ,  $g_1$ , and  $g_2$  in (14) with  $h_1 \triangleleft g_2$ ,  $g_3$ , and  $h_3 \triangleright g_4$ , respectively, we get that

$$\begin{aligned} & \tilde{u}((h_1 \triangleleft g_2)h_2, g_3, h_3 \triangleright g_4) + \tilde{v}(h_1 \triangleleft g_2, h_2, g_3(h_3 \triangleright g_4)) \\ &= \tilde{u}(h_2, g_3, h_3 \triangleright g_4) + \tilde{u}(h_1 \triangleleft g_2, h_2 \triangleright g_3, (h_2 \triangleleft g_3) \triangleright (h_3 \triangleright g_4)) \\ & \quad + \tilde{v}((h_1 \triangleleft g_2) \triangleleft (h_2 \triangleright g_3), h_2 \triangleleft g_3, h_3 \triangleright g_4) + \tilde{v}(h_1 \triangleleft g_2, h_2, g_3). \end{aligned}$$

Use the above to replace the sum of the 3rd and 8th terms in the previous expression, collect the terms with  $\tilde{u}$  and  $\tilde{v}$ , and apply (12) and (13) to get 0.  $\square$

**Lemma 2.** *Let a pair  $(\tilde{u}_1, \tilde{v}_1)$  satisfy (15) with  $\tilde{u}_2 = \tilde{v}_2 = 0$ . Then  $f_1$  defined by (16) for  $(\tilde{u}_1, \tilde{v}_1)$  is a 1-coboundary.*

*Proof.* With the notations as before, we have

$$\begin{aligned} f_1(k_1, k_2, k_3) &= \tilde{u}_1(h_1, g_2, h_2 \triangleright g_3) + \tilde{v}_1(h_1 \triangleleft g_2, h_2, g_3) \\ &= \tilde{r}(h_1, g_2) + \tilde{r}(h_1 \triangleleft g_2, h_2 \triangleright g_3) - \tilde{r}(h_1, g_2(h_2 \triangleright g_3)) \\ & \quad + \tilde{r}((h_1 \triangleleft g_2)h_2, g_3) - \tilde{r}(h_1 \triangleleft g_2, h_2 \triangleright g_3) - \tilde{r}(h_2, g_3). \end{aligned}$$

On the other hand, extending  $\tilde{r}$  from  $H \times G \rightarrow \tilde{\mathbb{T}}$  to  $K \times K \rightarrow \tilde{\mathbb{T}}$  by setting  $\tilde{r}(g_1 h_1, g_2 h_2) = \tilde{r}(h_1, g_2)$ , we have

$$\begin{aligned} (d^1 \tilde{r})(k_1, k_2, k_3) &= \tilde{r}(k_2, k_3) - \tilde{r}(k_1 k_2, k_3) + \tilde{r}(k_1, k_2 k_3) - \tilde{r}(k_1, k_2) \\ &= \tilde{r}(h_2, g_3) - \tilde{r}((h_1 \triangleleft g_2)h_2, g_3) + \tilde{r}(h_1, g_2(h_2 \triangleright g_3)) - \tilde{r}(h_1, g_2). \end{aligned}$$

Comparing the above, we see that  $f_1 = d^1(-r)$ .  $\square$

**Corollary 1.** *The map  $\theta$  is well-defined.*

**Lemma 3.** *Let  $f \in {}_G H_H^2$ . Then  $f$  satisfies the following:*

$$f(k_1, k_2, k_3) = f(h_1, g_2, h_2 \triangleright g_3) + f(h_1 \triangleleft g_2, h_2, g_3).$$

*Proof.* Since  $f$  is a 2-cocycle,

$$\begin{aligned} 0 &= (d^2 f)(h_1, g_2, h_2, g_3) = f(g_2, h_2, g_3) - f(h_1 g_2, h_2, g_3) + f(h_1, g_2 h_2, g_3) \\ & \quad - f(h_1, g_2, h_2 g_3) + f(h_1, g_2, h_2). \end{aligned}$$

But  $f(g_2, h_2, g_3) = f(e_K, h_2, g_3) = 0$ ,  $f(h_1 g_2, h_2, g_3) = f(h_1 \triangleleft g_2, h_2, g_3)$ ,  $f(h_1, g_2, h_2 g_3) = f(h_1, g_2, h_2 \triangleright g_3)$ , and  $f(h_1, g_2, h_2) = f(h_1, g_2, e_K) = 0$ .  $\square$

**Corollary 2.** *The map  $\theta$  is a surjection.*

*Proof.* For  $f \in {}_G H_H^2$ , define  $\tilde{u}(h_1, g_2, g_3) = f(h_1, g_2, g_3)$  and  $\tilde{v}(h_1, h_2, g_3) = f(h_1, h_2, g_3)$ . Then  $\tilde{u}$  and  $\tilde{v}$  satisfy (12), (13), and (14).  $\square$

**Lemma 4.** *The map  $\theta$  is an injection.*

*Proof.* Indeed, let  $\theta([u, v])(k_1, k_2, k_3) = (d^1 \tilde{r})(k_1, k_2, k_3)$ , that is,

$$\begin{aligned} & \tilde{u}(h_1, g_2, h_2 \triangleright g_3) + \tilde{v}(h_1 \triangleleft g_2, h_2, g_3) \\ &= \tilde{r}(k_2, k_3) - \tilde{r}(k_1 k_2, k_3) + \tilde{r}(k_1, k_2 k_3) - \tilde{r}(k_1, k_2) \\ &= \tilde{r}(h_2, g_3) - \tilde{r}((h_1 \triangleleft g_2) h_2, g_3) + \tilde{r}(h_1, g_2 (h_2 \triangleright g_3)) - \tilde{r}(h_1, g_2). \end{aligned}$$

By setting  $h_2 = e_H$  and then  $g_2 = e_G$ , we obtain

$$\begin{aligned} \tilde{u}(h_1, g_2, g_3) &= -\tilde{r}(h_1 \triangleleft g_2, g_3) + \tilde{r}(h_1, g_2 g_3) - \tilde{r}(h_1, g_2) \\ \tilde{v}(h_1, h_2, g_3) &= \tilde{r}(h_2, g_3) - \tilde{r}(h_1 h_2, g_3) + \tilde{r}(h_1, h_2 \triangleright g_3), \end{aligned}$$

that is  $[u, v] = [1, 1]$ .  $\square$

Now, Corollaries 1, 2 and Lemma 4 prove the theorem.

## 2. An example for the Heisenberg group

As follows from (16), to find the functions  $\tilde{u}$ ,  $\tilde{v}$ , we need to construct a 2-cocycle  $f$  of the complex (9). Note that  $f$  is, actually, a 3-cocycle of the group  $K$  [7] satisfying the additional relations (6), (7).

Thus we construct a 3-cocycle  $F$  for the corresponding matched pair of the Lie algebras,  $(\mathfrak{g}, \mathfrak{h})$ , by using Proposition 1 in [5], find nonequivalent 3-cocycles in terms of Proposition 2 in [5], and consider the corresponding left-invariant form  $\omega_F$  on  $K$ . Following the procedure of finding a 3-cocycle on a Lie group from a 3-cocycle on the Lie algebra [7], we consider the 3-simplex  $\sigma$  given by

$$\begin{aligned} \sigma(h_1, g_2 h_2, g_3) &= \left( h_1 \triangleright (g_2 \cdot (h_2 \triangleright g_3^{p_3}))^{p_2} \right) \\ &\quad \cdot \left( (h_1 \triangleleft (g_2 (h_2 \triangleright g_3^{p_3})))^{p_2} (h_2 \triangleleft g_3^{p_3})^{q_2} \right)^{q_1}, \end{aligned} \quad (17)$$

where  $p_j, q_j : \Delta_3 \rightarrow \mathbb{R}$  are some differentiable functions on the standard 3-simplex  $\Delta_3 = \{(t_1, t_2, t_3) \in \mathbb{R}^3 : t_1, t_2, t_3 \geq 0, t_1 + t_2 + t_3 \leq 1\}$ . Then the 2-cocycle  $f$  can be found in the form

$$f(h_1, g_2 h_2, g_3) = \int_{\sigma(h_1, g_2 h_2, g_3)} \omega_F. \quad (18)$$

Using the above procedure, we now construct pairs of continuous co-cycles  $(\tilde{u}, \tilde{v})$  for the matched pair of Lie groups  $(G, H)$  associated with the Heisenberg group. Denote

$$g(\vec{a}) = \begin{pmatrix} 1 & \vec{0}^t & 0 \\ \vec{0} & 1_n & \vec{a} \\ 0 & \vec{0}^t & 1 \end{pmatrix}, \quad h(\vec{x}, y) = \begin{pmatrix} 1 & \vec{x}^t & y \\ \vec{0} & 1_n & \vec{0} \\ 0 & \vec{0}^t & 1 \end{pmatrix},$$

where  $\vec{a}, \vec{x} \in \mathbb{R}^n$ ,  $y \in \mathbb{R}$ ,  $\vec{x}^t$  is the transpose of  $\vec{x}$ , and  $1_n$  denotes the unit matrix on  $\mathbb{R}^n$ . The groups  $G = \{g(\vec{a}) : \vec{a} \in \mathbb{R}^n\}$  and  $H = \{h(\vec{x}, y) : \vec{x} \in \mathbb{R}^n, y \in \mathbb{R}\}$  form a matched pair of Abelian Lie groups with the mutual actions

$$h(\vec{x}, y) \triangleright g(\vec{a}) = g(\vec{a}), \quad h(\vec{x}, y) \triangleleft g(\vec{a}) = h(\vec{x}, y + \vec{a} \cdot \vec{x}),$$

where  $\vec{a} \cdot \vec{x}$  is the scalar product of  $\vec{a}, \vec{x} \in \mathbb{R}^n$ .

Thus the group  $K = GH$  is the Heisenberg group, that is, the group of matrices of the form

$$\begin{pmatrix} 1 & \vec{x}^t & y \\ \vec{0} & 1_n & \vec{a} \\ 0 & \vec{0}^t & 1 \end{pmatrix}.$$

Consider the corresponding matched pair of the Abelian Lie algebras  $(\mathfrak{g}, \mathfrak{h})$ . The Lie algebras  $\mathfrak{g}$  and  $\mathfrak{h}$  consist of the matrices

$$\begin{pmatrix} 0 & \vec{0}^t & 0 \\ \vec{0} & 0_n & \vec{a} \\ 0 & \vec{0}^t & 0 \end{pmatrix}, \quad \begin{pmatrix} 0 & \vec{x}^t & y \\ \vec{0} & 0_n & \vec{0} \\ 0 & \vec{0}^t & 0 \end{pmatrix},$$

respectively. Let  $A_j \in \mathfrak{g}$ ,  $j = 1, \dots, n$ , denote the matrix with  $\vec{a}$  having 1 at the  $j$ th place and the rest 0. The matrices  $X_j$  and  $Y$  are defined similarly. Then  $A_j, X_j, Y$  form a basis in the Lie algebra  $\mathfrak{k}$  of the Lie group  $K$ . The mutual actions are given by

$$X_j \triangleleft A_k = \delta_{jk} Y, \quad Y \triangleleft A_j = X_j \triangleright A_k = Y \triangleright A_k = 0,$$

where  $\delta_{jk}$  denotes Kronecker's symbol.

Using Propositions 1, 2 in [5] we find that the functionals  $F_{jkl}^1$  and  $F_{jkl}^2$ , defined on the basis of the Lie algebra  $\mathfrak{k}$  by

$$F_{jkl}^1(X_j, X_k, A_l) = 1, \quad 1 \leq j < k \leq n, \quad l = 1, \dots, n, \quad (19)$$

and zero on other basis elements, and

$$F_{jkl}^2(X_j, A_k, A_l) = 1, \quad j = 1, \dots, n, \quad 1 \leq k < l \leq n, \quad j \neq k, \quad j \neq l, \quad (20)$$

and zero otherwise, make a basis in the space of equivalence classes of 3-cocycles for the matched pair of Lie algebras  $(\mathfrak{g}, \mathfrak{h})$ . Thus the dimension of the corresponding cohomology group of the matched pair of the Lie algebras is  $n(n-1)^2$ .

The left-invariant 3-forms on  $K$  that correspond to  $F_{jkl}^1$  and  $F_{jkl}^2$  are

$$\omega_{jkl}^1 = dx^j \wedge dx^k \wedge da^l, \quad \omega_{jkl}^2 = dx^j \wedge da^k \wedge da^l,$$

where  $x^j$  denotes the  $j$ -th coordinates of  $\vec{x} \in \mathbb{R}^n$ .

Using (16), (17) and (18), we obtain the corresponding pairs of cocycles  $\tilde{u}, \tilde{v}$  for the matched pair  $(G, H)$ ,

$$\begin{aligned} \tilde{u}_{jkl}^1(h(\vec{x}, y), g(\vec{a}_1), g(\vec{a}_2)) &= 0, \\ \tilde{v}_{jkl}^1(h(\vec{x}_1, y_1), h(\vec{x}_2, y_2), g(\vec{a})) &= a^l \begin{vmatrix} x_1^j & x_2^j \\ x_1^k & x_2^k \end{vmatrix}, \end{aligned} \quad (21)$$

where  $j < k, l = 1, \dots, n$ , and

$$\begin{aligned} \tilde{u}_{jkl}^2(h(\vec{x}, y), g(\vec{a}_1), g(\vec{a}_2)) &= x^j \begin{vmatrix} a_1^k & a_2^k \\ a_1^l & a_2^l \end{vmatrix}, \\ \tilde{v}_{jkl}^2(h(\vec{x}_1, y_1), h(\vec{x}_2, y_2), g(\vec{a})) &= 0, \end{aligned} \quad (22)$$

for  $j < k, j \neq k, j \neq l$ .

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